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UNITED STATES PATENT APPLICATION

FOR

**STATIC COMPILATION OF INSTRUMENTATION
CODE FOR DEBUGGING SUPPORT**

INVENTOR:

Guei-Yuan Lueh

PREPARED BY:

BLAKELY, SOKOLOFF, TAYLOR & ZAFMAN LLP
12400 Wilshire Blvd., 7th Floor
Los Angeles, CA 90025-1026
(714) 557-3800

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STATIC COMPILATION OF INSTRUMENTATION

CODE FOR DEBUGGING SUPPORT

BACKGROUND

1. Field of the Invention

[0001] This invention relates to compiler. In particular, the invention relates to debugger support.

2. Background of the Invention

[0002] Traditional compilers embed the symbol table information into the executables during compilation. After parsing symbol table information and creating efficient data structures to store this information, the debugging and other programming tools can use the symbol table information during their executions.

[0003] The amount of memory storage to store the symbol table information may be large. Some compilers may have a limit on the amount of valid symbol table information that can be used. Examples of such compilers include Java compilers. A static Java compiler converts Java source code into a verifiably secure and compact architecture-neutral intermediate format, call Java byte codes. A Java Virtual Machine interprets the byte code instructions at run time. To improve run-time performance, a Just-In-Time (JIT) Java compiler produces native code from Java byte code instructions during program execution. However, the symbol table information generated by the Java language is not sufficient to be used by the JIT compiler to provide debugging support. This is because the symbol table information in class files is generated for architecture independent byte codes while the JIT compiler generates machine specific instructions.

[0004] Existing techniques to provide debugging support have a number of drawbacks. One technique is to construct additional data structures and store all the information that might possibly be used in the future. This technique increases the memory requirement significantly. Another technique is to simulate the translation of byte codes to native instructions and to produce the information when needed. This technique unduly degrades execution performance.

[0005] Therefore, there is a need for a technique to provide efficient debugging support.

BRIEF DESCRIPTION OF THE DRAWINGS

[0006] The features and advantages of the present invention will become apparent from the following detailed description of the present invention in which:

[0007] Figure 1 is a diagram illustrating a system in which one embodiment of the invention can be practiced.

[0008] Figure 2 is a diagram illustrating a platform debugger architecture shown in Figure 1 according to one embodiment of the invention.

[0009] Figure 3 is a diagram illustrating an application shown in Figure 2 according to one embodiment of the invention.

[0010] Figure 4 is a diagram illustrating a debugging support shown in Figure 3 according to one embodiment of the invention.

[0011] Figure 5 is a diagram illustrating a static and semi-static data access support shown in Figure 4 according to one embodiment of the invention.

[0012] Figure 6 is a diagram illustrating a dynamic data access support shown in Figure 4 according to one embodiment of the invention.

[0013] Figure 7 is a diagram illustrating an example for the static data access support shown in Figure 5 according to one embodiment of the invention.

[0014] Figure 8 is a diagram illustrating an example for the semi-static data access support shown in Figure 5 according to one embodiment of the invention.

[0015] Figure 9 is a diagram illustrating an example for the dynamic data access support shown in Figure.6 according to one embodiment of the invention.

[0016] In the following description, for purposes of explanation, numerous details are set forth in order to provide a thorough understanding of the present invention. However, it will be apparent to one skilled in the art that these specific details are not required in order to practice the present invention. In other instances, well-known electrical structures and circuits are shown in block diagram form in order not to obscure the present invention. For examples, although the description of the invention is directed to the Java debugging architecture platform, the invention can be practiced for other debugging architecture platforms having similar characteristics.

[0018] The processor 110 represents a central processing unit of any type of architecture, such as embedded processors, micro-controllers, digital signal processors, superscalar computers, vector processors, single instruction multiple data (SIMD) computers, complex instruction set computers (CISC), reduced instruction set computers (RISC), very long instruction word (VLIW), or hybrid architecture. In one embodiment, the processor 110 is compatible with the Intel Architecture (IA) processor, such as the IA-32 and the IA-64. The host bus 120 provides interface signals to allow the processor 110 to communicate with other

processors or devices, e.g., the MCH 130. The host bus 120 may support a uni-processor or multiprocessor configuration. The host bus 120 may be parallel, sequential, pipelined, asynchronous, synchronous, or any combination thereof.

[0019] The MCH 130 provides control and configuration of memory and input/output devices such as the system memory 140 and the ICH 150. The MCH 130 may be integrated into a chipset that integrates multiple functionalities such as the isolated execution mode, host-to-peripheral bus interface, memory control. For clarity, not all the peripheral buses are shown. It is contemplated that the system 100 may also include peripheral buses such as Peripheral Component Interconnect (PCI), accelerated graphics port (AGP), Industry Standard Architecture (ISA) bus, and Universal Serial Bus (USB), etc.

[0020] The system memory 140 stores system code and data. The system memory 140 is typically implemented with dynamic random access memory (DRAM) or static random access memory (SRAM). The system memory may include program code or code segments implementing one embodiment of the invention. The system memory 140 includes a platform debugger architecture 145. The platform debugger architecture 145 may also be implemented by hardware, software, firmware, microcode, or any combination thereof. The system memory 140 may also include other programs or data, which are not shown, such as an operating system. The instruction code stored in the memory 140, when executed by the processor 110, causes the processor to perform the tasks or operations as described in the following.

[0021] The ICH 150 has a number of functionalities that are designed to support input/output I/O functions. The ICH 150 may also be integrated into a chipset together or separate from the MCH 130 to perform I/O functions. The ICH 150 may include a number of interface and I/O functions such as PCI bus interface, processor interface, interrupt controller, direct memory access (DMA) controller, power management logic, timer, universal serial bus (USB) interface, mass storage interface, low pin count (LPC) interface, etc.

[0022] The mass storage device 170 stores archive information such as code, programs, files, data, applications, and operating systems. The mass storage device 170 may include compact disk (CD) ROM 172, floppy diskettes 174, and hard drive 176, and any other magnetic or optic storage devices. The mass storage device 170 provides a mechanism to read machine-readable media.

[0023] The I/O devices 180₁ to 180_K may include any I/O devices to perform I/O functions. Examples of I/O devices 180₁ to 180_K include controller for input devices (e.g., keyboard, mouse, trackball, pointing device), media card (e.g., audio, video, graphics), network card, and any other peripheral controllers.

[0024] The present invention may be implemented by hardware, software, firmware, microcode, or any combination thereof. When implemented in software, firmware, or microcode, the elements of the present invention are the program code or code segments to perform the necessary tasks. A code segment may represent a procedure, a function, a subprogram, a program, a routine, a subroutine, a module, a software package, a class, or any combination of instructions, data structures, or program statements. A code segment may be coupled to another code segment or a hardware circuit by passing and/or receiving information, data, arguments, parameters, or memory contents. Information, arguments, parameters, data, etc. may be passed, forwarded, or transmitted via any suitable means including memory sharing, message passing, token passing, network transmission, etc. The program or code segments may be stored in a processor readable medium or transmitted by a computer data signal embodied in a carrier wave, or a signal modulated by a carrier, over a transmission medium. The "processor readable medium" may include any medium that can store or transfer information. Examples of the processor readable medium include an electronic circuit, a semiconductor memory device, a ROM, a flash memory, an erasable ROM (EROM), a floppy diskette, a compact disk CD-ROM, an optical disk, a hard disk, a fiber optic medium, a radio frequency (RF) link, etc. The computer data signal may include any signal that can propagate over a transmission medium such as electronic network channels, optical fibers, air,

identified as hot methods based on the collected profiling information and generates the optimized native code 360.

[0030] The debug support 370 includes a number of debugging support mechanisms to enhance the debug performance. The debug support 370 provides instrumentation code to be used by the fast code generator 330 for accessing data values, stack frame, and manipulating control and data break points.

[0031] Figure 4 is a diagram illustrating the debugging support 370 shown in Figure 3 according to one embodiment of the invention. The debug support 370 includes a stack frame access support 410, a data value access support 420, a control break-point support 430, and a data break-point support 440.

[0032] The stack frame access support 410 provides support for stack frame accesses. For stack frame accesses, the JIT compiler provides a mechanism to identify and access the caller's frame context, referred to as unwinding stack frame. The stack unwinding process starts with a frame context of the caller. If the active frame belongs to a Java method compiled by JIT compiler (referred to as jitted method), the VM makes calls to the compiler to perform the unwinding operation. This is due to the fact that the compiler has all information about the layout of the frames. The information about the return *ip*, location and size of spill area, location for saving callee-save registers and outgoing arguments can be obtained from JIT compiler for jitted methods. However, if the active frame does not belong to any jitted method, the VM uses its internal data structures to find the caller's context.

[0033] A Garbage Collection (GC) map is generated during compilation for each method, allowing the compiler to unwind stack frames for exception and compute the root set of live references for garbage collection. The GC map can be computed by a lazy approach. A small GC map, which contains some minimal but essential information, is generated when a method is compiled for the first time after its first invocation. JIT compiler recompiles the method to produce full

[0034] The data value access support 420 provides access to values of variables or contents of memory location at any time during program execution. The fast code generator performs simple register allocation during native code generation by mapping local variables to dedicated registers or locations in the spill area. To support data-value accesses, JIT compiler provides a run-time library function call that returns the address of the location where a local variable resides. The address of the variable can be either in the spill area of stack frame or the callee-save area depending on whether or not the variable was assigned to a callee-save register during the simple register allocation phase. The run-time library function call retrieves the address of the variable in three steps: First, the full GC map is retrieved. Dynamic recompilation of a method happens at this point if the full GC map does not already exist. Second, the JIT compiler constructs the frame context for the current method to figure out the stack frame layout of the method. Finally, the JIT compiler uses the mapping of registers to variables, stored in the GC map, to compute the address of the variable.

[0035] The control breakpoint support 430 allows user to stop program execution at desired locations or when certain conditions are satisfied.

Breakpoints can be implemented using two different techniques: trap patching and code patching. Traps to the operating systems introduce a significant overhead to transferring control to the operating system. Assembling the replacement code in a stub and replacing a segment of original code using branch or jump instructions into the stub usually implement code patching. Code patching has no intervention from the operating system since it transfers control directly via the replacement code. Both approaches provide a location map where the original code needs to be replaced with a branch or trap instruction.

[0036] The fast code generator 330 (Figure 3) performs several simple optimizations such as strength reduction and constant folding during compilation

of byte codes to the native code. It does not perform more aggressive optimizations such as code motion, dead code elimination, or instruction scheduling, which could potentially cause the code location problem. The lazy code selector passes over the byte code sequence and generates a sequence of native instructions for each byte code. The generated native instruction sequence is emitted to a code buffer that is used later to update branch offsets and read-only data section offsets. During the emission of native code, the JIT compiler keeps track of both the following emit offset in the code buffer and the offset of the byte code stream. The code location map is computed using both the byte code and the emit offset.

[0037] The JIT compiler does not generate the code location map until it is needed. That is, when a method is first compiled the code location map is not generated. However, when a breakpoint is set or cleared, the code location map is generated using dynamic recompilation. To set or clear a breakpoint, the JIT compiler provides an interface function call to a runtime library function, that triggers dynamic recompilation and returns the native code offset for a given byte code in a method. As soon as the lazy code selector reaches the byte code offset, the recompilation is terminated and the next emit offset is returned. The location map generated for future uses may not be stored since recompilation is transparent to the users and it produces the information needed efficiently without introducing a significant runtime overhead.

[0038] The data break-point 440 provides users with a mechanism to stop the program execution in terms of the program's memory states. Data break-points are also referred to as watch points. Java is a type safe language that does not allow arbitrary memory updates in the heap. Therefore, JVMDI does not have the interface that monitors any arbitrary memory location but have the support for field watches. Data breakpoint is one of the crucial features for tracking or isolating bugs in software that are otherwise hard or even impossible to find. The data break-point support 440 includes a field access and modifications watch 445 to provide support for field watches.

[0044] The field access and modification watch 445 has three models or approaches static, semi-static, and dynamic. The three models, or approaches, differ by *where* and *when* the additional instrumentation code is inserted and *how* the execution of the instrumentation code is guarded during debugging support. In the static model, the additional code is inserted in method's address space at compilation time and its execution is guarded using a Boolean flag. In the semi-static model, the additional code is inserted at the end of the method's code space and/or a no-op (NOP) instruction sequence is inserted to the location that access or modify fields. The execution of the instrumentation code is guarded by changing NOP instruction sequence to a jump instruction. In the dynamic model, dynamic recompilation is used to insert the instrumentation code when needed. All three models or use the same mechanism to pass the arguments to and call the run-time library function that calls the event hook function.

[0045] Figure 5 is a diagram illustrating a static and semi-static data access support 445 shown in Figure 4 according to one embodiment of the invention. The static and semi-static data access support 445 includes a compilation 505 generation of an instrumentation code 510, a guard of execution 530, and an insertion of instrumentation code 550. Both static and semi-static models insert

field watch sequence (Block 544). Either one of the blocks 542 and 544 occurs at run time when the field watches are activated.

[0049] The insertion 550 inserts the instrumentation code to the native code from the compilation 505. For the static model, the insertion 550 inserts the instrumentation code before a field access or modification point (Block 552). For the semi-static model, the insertion 550 inserts the instrumentation code at the end of the code space of the compiled function (Block 554).

[0050] Unlike the static model, the semi-static model executes fewer instructions when no field watch is activated because only one jump instruction is executed. However, when the field watch is activated, the semi-static model executes more instructions because of the additional code to maintain the state of registers and memory consistent. The semi-static model also reduces the instruction cache misses by inserting the instrumentation code at the end of the method's code space, assuming that the user is less likely to activate many field watches at a time.

[0051] To activate or clear a field watch, the JVM needs to keep track of the locations where the jump zero instructions are inserted. Unlike the static model, field watch activating or clearing is linear in the number of locations the field is accessed or modified. Additionally, during the compilation of a method, if any field watch is already activated for a field that the method accesses or modifies, the jump instruction is inserted with the offset to the instrumentation code, and not zero.

[0052] Figure 6 is a diagram illustrating the dynamic data access support 445 shown in Figure 4 according to one embodiment of the invention. The dynamic data access support 445 includes a compilation 601 and a recompilation 602.

[0053] The compilation 601 is the first or initial compilation. It includes a compilation of byte code 605 and a guard of execution 610. The compilation of

byte code 605 compiles a byte code sequence having a field byte code that accesses or modifies a field. In one embodiment, the field byte code may be one of a getfield, getstatic, putfield, and putstatic byte codes as defined by the JVM specification (e.g., The Java TM Virtual Machine Specification, Second edition, by Tim Lindholm and Frank Yellin, published by Addison-Wesley, 1999).

[0054] The guard 610 prevents execution of the instrumentation code if the field watch is not activated. The guard 610 may be implemented by two methods: (1) updating an offset of a jump instruction to the stub when the field watch is activated (Block 622), and (2) replacing a no-op sequence with a jump instruction to the stub (Block 624). The use of a jump instruction is simpler because it merely involves a change of the offset. To clear the field watch, the compiler may either replace the offset of the jump instruction with a zero offset, or replace the jump instruction with a no-op sequence.

[0055] The recompilation 602 recompiles a function including the byte code sequence when the field watch is activated. Since it is performed by the fast code generator, the execution is fast and efficient. The recompilation 602 includes the compilation of byte code 605, the guard 610, a generation of instrumentation code 630, and an insertion instrumentation code 650. The generation 630 is essentially similar to the generation 510 (Figure 5). It generates an instrumentation code corresponding to a field watch of the field. The generation 630 includes an execution 640 of a field watch sequence if the field watch is activated. The execution 640 includes saving live global state (Block 642), executing an event hook function for an event corresponding to the field watch (Block 644), and restoring the live global state (Block 646). The live global state corresponds to an active register such as a live scratch register or a floating-point register. In one embodiment, saving the live global state includes pushing the live global state onto a stack, and restoring the saved live global state includes retrieving it from the stack. The execution of the event hook function includes passing an argument corresponding to the field and calling a run-time library function related to the event.

[0056] The insertion 650 is similar to the insertion 550 for a semi-static model. It inserts the instrumentation code to the native code. In one embodiment, the insertion 650 inserts the instrumentation code in a stub at the end of the code space of the method.

[0057] When the field watch is activated, the JIT compiler performs three operations. First, the JIT compiler computes the necessary information for the instrumentation code. Second, the JIT compiler inserts the instrumentation code into the stub. Third, the JIT compiler updates the offset of the jump instruction into the stub containing the field watch sequence of the instrumentation code. In other words, if the field watch is not activated, the stub and the instrumentation code are not generated. In addition, if the field watch is not activated, the offset of the jump instruction is not updated.

[0058] Insertion of the jump zero instruction or no-op sequence is only one way to guard the execution of the instruction code. Alternatively, the JIT compiler may relocate several of the original instructions to the stub and replants it with a jump instruction into the stub.

[0059] In the dynamic re-compilation, the JIT compiler stores a map from field access and modification points to their stub addresses, if already generated. The generated stubs remain in the code space even after the corresponding field watch is cleared. In other words, the dynamic re-compilation is performed when the stub for a field access or modification point does not exist. Like in the semi-static model, if a field watch is already activated, the JIT compiler generates the stub and inserts the jump to the stub during the compilation of the method. Clearing a field watch replaces the offset of the jump instruction with zero.

[0060] Figure 7 is a diagram illustrating an example for the static data access support shown in Figure 5 according to one embodiment of the invention.

[0061] The byte code "getfield #42" retrieves the value of a non-static field, numbered 42 (line 2), and compares it with the integer value in local register

4 (line 11). Lines 3-5 show the native instruction sequence to spill the mimic stack operands, which are live at the field access point, to their canonical spill locations. This spill code is executed during program execution even though the field access watch may not be activated. This is performed for consistency in memory state, garbage collection, and exception handling tasks.

[0062] Lines 6-7 correspond to the guarding function to guard execution of the instrumentation code (lines 8-10). The guard operation takes advantage of the flag usage in the JVM. The JVM stores a Boolean field for each class field in its internal data structures. This Boolean flag is set to true when the field watch is activated and to false when the field watch is cleared. By comparing this flag with this predetermined watch value (e.g., true, or logical 1), the code can determine if the field watch is activated. If the flag is not the same as the watch value, then control passes to NoWatch (line 13), or continuation of the normal byte code execution. Otherwise, lines 8-10 are executed.

[0063] Lines 8-10 correspond to the field watch sequence. The execution of the field watch sequence includes passing arguments (e.g., pointer to the internal structure for the field) and calling a run-time library function (line 10).

[0064] Figure 8 is a diagram illustrating an example for the semi-static data access support shown in Figure 5 according to one embodiment of the invention.

[0065] The byte code sequence retrieves the value of a non-static field, numbered 159 (line 3) and casts it to double (line 6). Line 5 is the guard to prevent the instrumentation code (lines 14-25) from being executed when the field watch is not activated. This guard is a jump instruction. The offset of this jump instruction is zero initially before the field watch is activated.

[0066] When the field watch is activated, the JIT compiler changes the offset of the jump instruction into the stub containing the field watch sequence of the instrumentation code (line 14). During the lazy code selection, the JIT

compiler assumes that the jump to the instrumentation code is not taken. Therefore, no spill code is generated for mimic stack operands at the field access point (line 4). Spilling is delayed until the instrumentation code is actually executed (line 14). Since spilling does not happen at field access or modification points, the global state is saved before the event hook function and is restored afterwards. The global state varies depending on the type of the field access or modification. To maintain consistency for state of memory and registers, any register that is live at the point of instrumentation code execution is saved. For example, line 14 saves the scratch register `eax` by pushing it onto the stack. Line 24 restores the saved scratch register by retrieving from the stack. Similarly, line 19 is a spill code for floating point values. Line 23 restores the floating point values.

[0067] Lines 20 and 21 pass the necessary information before calling to the run-time library function. The first argument is a pointer to the internal structure for the field. The second argument is the pointer to the object being accessed. Line 22 is the call to the run-time library function related to the event.

[0068] Figure 9 is a diagram illustrating an example for the dynamic data access support shown in Figure 6 according to one embodiment of the invention.

[0069] The byte code sequence for the dynamic re-compilation is essentially the same as the semi-static model except that the stub containing the instrumentation code is recompiled when the field watch is activated.

[0070] The byte code sequence retrieves the value of a non-static field, numbered 159 (line 3) and casts it to double (line 6). Line 5 is the guard to prevent the instrumentation code contained in the stub from being executed when the field watch is not activated. This guard is a jump instruction. The offset of this jump instruction is zero initially before the field watch is activated.

